Lecture 3: (Hyper)Properties, Robustness and Property-Preserving Compilers

CS350

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Properties and Hyperproperties

- Formalise any security property
- Established theory with practical applications

Recommended reading:

- Schneider. 2000. Enforceable security policies.
- Alpern and Schneider. 1985. Defining liveness.
- Clarkson and Schneider. 2010. Hyperproperties.

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 - component-context interactions α ? α !...
 - code-environment interaction $\mathit{read}\ v; \mathit{write}\ v$

We use *t* abstractly now, though mostly:

$$t = \overline{\Theta}$$

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This is unlike program equivalence:

properties talk a single program

Examples

• NRW: $\{t \mid \nexists \Theta < \Theta'. \vdash read \Theta \land \vdash send \Theta'\}$ NRW: the program does not send on the network after reading a file

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 NRW: the program does not send on the network after reading a file
 ⊢ readΘ and ⊢ sendΘ' are abstract predicates
- GS: $\{t \mid \vdash req\Theta_i \Rightarrow \vdash resp\Theta_j \text{ where } j > i\}$ GS: the program eventually responds to the requests

Safety and Liveness

Properties are partitioned in

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- Liveness: something good eventually happens (GS)

Safety

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- but, Safety = weak secrecy: we don't leak a fresh k to ${\mathfrak C}$

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- Describe safety by the so-called set of bad prefixes
- In the following: m is a finite trace t (a finite $\overline{\Theta}$) aka a prefix
- NRW-dual: $\{m \mid \Theta < \Theta'. \vdash read\Theta \land \vdash send\Theta'\}$

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- capture multiple runs (the sets of traces) of any program (the sets)

Example: NonInterference

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- NI: two different high inputs result in the same low outputs
- high = secret, low = public
- a set of traces tells all the behaviours of the same program with different high inputs

```
egin{cases} \mathsf{NI:} \ \left\{\{t_1,t_2\} \;\middle|\; egin{array}{l} \forall t_1,t_2 \in \{t_1,t_2\}. \ \ \mathsf{if\;inputs}\,(t_1) =_L \, \mathsf{inputs}\,(t_2) \ \ \mathsf{then\;outputs}\,(t_1) =_L \, \mathsf{outputs}\,(t_2) \ \end{array} 
ight\}
```

Example: Average Response Time < 1

ART:

$$\left\{ \left\{t\cdots\right\} \ \middle| \ \operatorname{mean}\left(\ \bigcup_{t \in \left\{t\cdots\right\}} \operatorname{response_time}\left(t\right) \ \right) < 1 \right\}$$

where response_time (\cdot) looks in trace t and checks time between req (\cdot) and resp (\cdot)

Hypersafety and Hyperliveness

Like Properties, Hyperproperties are partitioned in

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\begin{cases} \text{NI-dual:} \\ \left\{ \{t_1, t_2\} \middle| \begin{array}{c} \forall t_1, t_2 \in \{t_1, t_2\}. \\ \text{if inputs} \, (t_1) =_L \text{inputs} \, (t_2) \\ \text{then outputs} \, (t_1) \neq_L \text{outputs} \, (t_2) \\ \end{cases} \end{cases}
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- Property $\pi = \{t\}$
- $\vdash P : \pi \stackrel{\text{def}}{=} \text{ if } P \rightsquigarrow t \text{ then } t \in \pi$

How do we formalise a program having a hyperproperty?

• All traces generated by P: Behav $(P) = \{t \mid P \rightarrow t\}$.

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- $\vdash P : H \stackrel{\text{def}}{=} \text{Behav}(P) \in H$

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So we want our program P to satisfy NRW, GS, NI or ART: $\forall \mathfrak{C}.\mathfrak{C}[P]$, so $\Theta = \mathfrak{C}[P]$

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So we want our program P to satisfy NRW, GS, NI or ART: $\forall \mathfrak{C}.\mathfrak{C}[P]$, so $\Theta = \mathfrak{C}[P]$

Reminiscent of contextual equivalence!

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- $\vdash_R P : \pi \stackrel{\text{def}}{=} \forall \mathfrak{C}$. if $\mathfrak{C}[P] \rightsquigarrow t$ then $t \in \pi$
- $\vdash_R P : H \stackrel{\text{def}}{=} \forall \mathfrak{C}. \text{Behav} (\mathfrak{C}[P]) \in H$

A Note on Robustness

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- Contexts can generate property-relevant events now
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- we must filter events and consider only those generated by P

Example: Robust Safety

- $\pi \in Safety$
- $\vdash_R P : \pi \stackrel{\text{\tiny def}}{=} \forall \mathfrak{C}$. if $\mathfrak{C}[P] \leadsto t$ then $t \in \pi$

Example: Robust Safety

- $\pi \in Safety$
- $\vdash_R P : \pi \stackrel{\text{\tiny def}}{=} \forall \mathfrak{C}$. if $\mathfrak{C}[P] \rightsquigarrow t$ then $t \in \pi$
- dually: $\{m\} :: \pi \in Safety$
- $m \le t$ = m is a prefix of t
- $\vdash_R P : \{m\} \stackrel{\text{def}}{=} \forall \mathfrak{C}. \text{ if } \mathfrak{C}[P] \rightsquigarrow t \text{ then } \not \equiv m \in \{m\}.m \leq t$

Example: Robust Liveness ...?

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- can this hold robustly?
- we need a fair context in our setup: a context that will interact with us
- avoid DOS: the attacker wants to violate our code, not starve it

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Q: can we preserve them through compilation?

Yes!

 specify (hyper)properties on programs through traces

2. Assumptions:

• same alphabet of traces between S and T (I/O or syscalls)

• we lift this (partially) later

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Assume the source has a property robustly

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$$RTP: \forall \pi. \ \forall \mathsf{P}. \ (\forall \mathfrak{C} \ t. \, \mathfrak{C}[\mathsf{P}] \rightsquigarrow t \Rightarrow t \in \pi) \Rightarrow$$
$$(\forall \mathfrak{C} \ t. \, \mathfrak{C}[[\![\mathsf{P}]\!]] \rightsquigarrow t \Rightarrow t \in \pi)$$

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RSP : \forall \pi \in Safety. \ \forall \mathsf{P}.
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Correct definitions

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Correct definitions
Hard to use: no proof support
We want equivalent criteria that are
easy to prove

$$RTP : \forall \pi. \ \forall \mathsf{P}. \ (\forall \mathfrak{C} \ t. \, \mathfrak{C}[\mathsf{P}] \to t \to t \in \pi) \to (\forall \mathfrak{C} \ t. \, \mathfrak{C}[[\mathsf{P}]] \to t \to t \in \pi)$$

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$$PFRTP : \forall \mathsf{P}. \ \forall \mathfrak{C}. \ \forall t. \ \mathfrak{C}[[\![\mathsf{P}]\!]] \rightsquigarrow t \Rightarrow$$

$$\exists \mathfrak{C}. \, \mathfrak{C}[\![\mathsf{P}]\!] \rightsquigarrow t$$

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Intuition

If any trace in the target is also done in the source, and the source has the property, so does the target.

$$\exists e.e[P] \rightarrow t$$

$$RSP : \forall \pi \in Safety. \ \forall \mathsf{P}.$$

$$(\forall \mathfrak{C} \ t. \ \mathfrak{C}[\mathsf{P}] \rightsquigarrow t \Rightarrow t \in \pi) \Rightarrow$$

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$$PFRSP : \forall \mathsf{P}. \ \forall \mathfrak{C}. \ \forall m.$$

$$\mathfrak{C}[[\mathsf{P}]] \rightsquigarrow m \Rightarrow$$

$$\exists \mathfrak{C}. \ \mathfrak{C}[\mathsf{P}] \rightsquigarrow m$$

Intuition

Safety is defined dually as a set of bad prefixes

If any prefix done in the target is also done in the source and the source has the safety property, that prefix is not bad, so the target also has the safety property

 $\exists \mathfrak{C}. \, \mathfrak{C}[\mathsf{P}] \rightsquigarrow m$

• $RTP \iff PFRTP$

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RHP : \forall H. \ \forall P. \ (\forall \mathfrak{C}. \operatorname{Behav} (\mathfrak{C}[P]) \in H) \Rightarrow (\forall \mathfrak{C}. \operatorname{Behav} (\mathfrak{C}[[P]]) \in H)
```

Example: Robust HP Preservation #2

$$RHP: \forall H. \ \forall \mathsf{P}. \ (\forall \mathfrak{C}. \, \mathsf{Behav} \, (\mathfrak{C}[\mathsf{P}]) \in H) \Rightarrow (\forall \mathfrak{C}. \, \mathsf{Behav} \, (\mathfrak{C}[[\mathsf{P}]]) \in H)$$

Example: Robust HP Preservation #2

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```
PFRHP : \forall P. \ \forall \mathfrak{C}. \ \exists \mathfrak{C}. \ Behav (\mathfrak{C}[\llbracket P \rrbracket]) = Behav (\mathfrak{C}[P])
PFRHP : \forall P. \ \forall \mathfrak{C}. \ \exists \mathfrak{C}. \ \forall t. \ \mathfrak{C}[\llbracket P \rrbracket] \rightarrow t \iff \mathfrak{C}[P] \rightarrow t
```

```
PFRTP : \forall P. \ \forall \mathfrak{C}. \ \forall t. \ \mathfrak{C}[\llbracket P \rrbracket] \rightarrow t \Rightarrow \exists \mathfrak{C}. \mathfrak{C}[P] \rightarrow t
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Quantifier ordering

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```

- Quantifier ordering
- Implication

in the H

Intuition

PFF

 Quantifier ordering: lifts to sets of traces since a c in PFRHP works for a set of traces

PFR

 Implication: a single implication means refinement, so the target can have more behaviours.
 Co-implication means no refinement, we need the exact same traces to ensure inclusion

Example: Robust Hypersafety Preservation

```
PFRHSP: \forall P. \forall \mathfrak{C}. \forall \{m\}. \{m\} \leq Behav(\mathfrak{C}[P]) \Rightarrow \exists \mathfrak{C}. \{m\} \leq Behav(\mathfrak{C}[P])
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PFRHSP: \forall P. \forall \mathfrak{C}. \forall \{m\}. \{m\} \leq Behav(\mathfrak{C}[P]) \Rightarrow \exists \mathfrak{C}. \{m\} \leq Behav(\mathfrak{C}[P])
```

Where \leq means *all* prefixes of $\{m\}$ are extended by the behaviour of the (compiled) program

 K-Hypersafety: hypersafety for sets of cardinality k (if k = 4, NMIF)

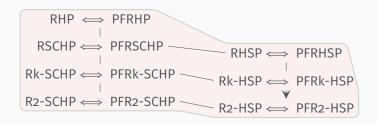
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- Subset-closed HP: set of traces closed under subsetting

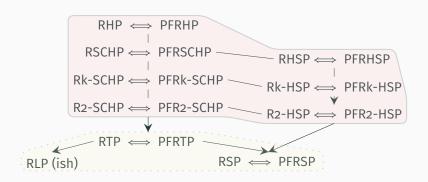
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- Hyperliveness: not present: RHLP collapses with RHP

Robust Compilation (RC) Diagram



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- both are robust
- FAC is only as precise as the equivalence
- RC do not preserve abstractions beyond the related security (hyper)property

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```

Recall \Rightarrow for FAC (contrapositive):

```
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PFRSP : \forall P. \ \forall \mathfrak{C}. \ \forall m.
\mathfrak{C}[\llbracket P \rrbracket] \rightsquigarrow m \Rightarrow \exists \mathfrak{C}. \ \mathfrak{C}[P] \rightsquigarrow m
\mathsf{Recall} \Rightarrow \mathsf{for} \ \mathsf{FAC} \ (\mathsf{contrapositive}):
\forall \mathsf{P}_1, \mathsf{P}_2
```

 $\exists \mathfrak{C}.\mathfrak{C}[\llbracket P_1 \rrbracket] \uparrow \iff \mathfrak{C}[\llbracket P_2 \rrbracket] \Rightarrow \exists \mathfrak{C}.\mathfrak{C}[P_1] \uparrow \iff \mathfrak{C}[P_2] \uparrow$

 $PFRTP : \forall P \forall \sigma \forall t$

Backtranslation!

 generate a c starting from what we have

Reca

 $\forall P_1,$

30.0



Backtranslation!

- generate a C starting from what we have
- \mathfrak{C} , t for PFRTP

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Reca



Backtranslation!

- generate a C starting from what we have
- \mathfrak{C} , t for PFRTP
- \mathfrak{C} , m for PFRSP

 $\forall P_1,$ $\exists \mathfrak{C}.\mathfrak{C}$

Reca



Backtranslation!

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- \mathfrak{C} , t for PFRTP
- \mathfrak{C} , m for PFRSP
- C, only!! for PFRHP

Reca

 $\forall P_1,$

3€.6



Backtranslation!

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- C, {m} for PFRHSP

Reca

 $\forall \mathsf{P}_1,$

3€.€



• $m/\{m\}$ yields trace-based BT

Reca $\forall P_1$,

[2]

- m/{m} yields trace-based BT
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 - or approximate BT (intuitively analogous to trace-based BT)

Reca $\forall P_1$,



- $m/\{m\}$ yields trace-based BT
- t is infinite, c is finite, so only use
 there
- e yields context-based BT
 - · can be precise BT
 - or approximate BT (intuitively analogous to trace-based BT)
- BT is not the inverse of compilation





Conclusion

We have seen:

- Properties and Hyperproperties: to formalise a program having a securty property
- Robust compilation criteria, which preserve classes of (hyper)properties
- Backtranslation-equivalent Robust compilation criteria

Suggested Reading

- Approximate CBT: will be presented in Fully-Abstract Compilation by Approximate Back-Translation
- Precise CBT: will be presented in Fully Abstract Compilation via Universal Embedding
- RC: Abate et al.. Journey Beyond Full Abstraction (formerly: Exploring Robust Property Preservation for Secure Compilation)